

METHODS OF APPLIED MATHEMATICS COMPREHENSIVE
EXAMINATION AUGUST 2015

Work on as many of the following problems as possible. Turn in *all* your work.

- (1) Consider two bodies of mass m_1 and m_2 , respectively, joined by a spring of constant k , in collinear motion along the z -axis of a cartesian frame in \mathbb{R}^3 . If the position of the first body is at $z = r_1(t)$ and the second is at $z = r_2(t)$, write down the evolution equations given by Newton's second law for these functions of time t , when both bodies are immersed in a gravitational force field $F = -GM_e m_j / r^2$, $j = 1, 2$, where r is the distance between the j -th body and the Earth's center, M_e are the Earth's and body's mass, respectively, and G is the universal gravitational constant.
- (a) Non-dimensionalize the equations of motion; assume $\epsilon \equiv m_2/m_1 \ll 1$, with $M_e \gg m_1$, and that the initial separation h between the two bodies is $0 < h \equiv r_1(0) - r_2(0)$, with $h \ll r_1(0)$.
- (b) Neglecting gravity, find the solution of these equations corresponding to zero initial velocities.
- (c) Write an asymptotic expansion of the equations of motion, and find the leading order terms of their solutions in the absence of gravity.
- (d) Assuming that the Earth is shrunk to a point at the origin and the gravitational interaction between m_1 and m_2 is negligible, find the leading order terms of the motion equations when gravity is included, and sketch the leading order solutions noting their time scale of validity.
- (2) Consider the following function of the complex variable z in the complex plane

$$f(z) = \frac{1}{\sqrt{z^2 - 1}} \operatorname{atan} \left(\frac{1}{\sqrt{z^2 - 1}} \right) :$$

- (a) Classify all singularities and propose branch cuts, if necessary, to make the function single valued on appropriate domains.
- (b) Discuss the convergence of the real integral

$$\int_{-1}^1 \frac{1}{\sqrt{|a^2 - t^2|}} \operatorname{atan} \left(\frac{1}{\sqrt{1 - t^2}} \right) dt$$

as a function of the real parameter a .

- (c) Propose a strategy for computing the real integral when $a = 1$ based on the study of the function $f(z)$. Discuss your proposal even if you cannot carry out all the steps to evaluate the value of the integral, if it is finite.

- (3) Consider the rapidly varying diffusivity:

$$K(x, y; \epsilon) = A + F(x/\epsilon^2) + G(y/\epsilon)$$

where A is chosen to guarantee K is positive, and ϵ is a small constant. By applying iterated homogenization, average the following diffusion equation subject to the rapidly varying "potential" $V(x/\epsilon^2) > 0$

$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left(K(x, y; \epsilon) \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(K(x, y; \epsilon) \frac{\partial u}{\partial y} \right) + V \left(\frac{x}{\epsilon^2} \right) u$$

$$u(x, y, 0) = u_0(x, y),$$

by computing a leading order effective equation governing the evolution as $\epsilon \rightarrow 0$ over the (x, y) -plane, assuming the functions $F(x)$, $V(x)$ and $G(y)$ are mean zero, periodic, and share the same period. Solve the averaged equation in free space.

- (4) Consider the 4th-order ordinary differential equation on the real line $x \in \mathbb{R}$,

$$\frac{d^4 y}{dx^4} = xy.$$

- (a) By using a contour integral representation in the appropriate complex Laplace-image plane, discuss whether solutions decaying as $|x| \rightarrow \infty$ exist.
 (b) Find the leading order asymptotic expansion of one of these solutions as $x \rightarrow \infty$ by appropriate deformations of the contour integral representation.

- (5) Consider the eigenvalue problem on the real line $x \in \mathbb{R}$

$$\epsilon y'' + (\cos^2(x) + \lambda)y = 0, \quad y(x) < \infty, \text{ as } |x| \rightarrow \infty.$$

- (a) Identify the range of λ for bounded eigenfunctions to exist.
 (b) As $\epsilon \rightarrow 0$ compute acceptable solutions by WKB approach in this limit.

- (6) Find two term asymptotic expansions as $\epsilon \rightarrow 0$ for all roots of the equation:

$$\epsilon z^4 + z^2 - 2z + 1 = \epsilon$$

- (7) Consider the following initial value problem for the equation

$$u_t + (\epsilon + x)u_x = \epsilon u u_x, \quad u(x, 0) = u_0(x),$$

where ϵ is a fixed nonzero small real parameter.

- (a) Solve with the method of characteristics for $\epsilon = 0$ and all times $t \geq 0$ on the real line x assuming the initial condition $u_0(x)$ is a "nice" function decaying as $|x| \rightarrow \infty$.
 (b) Set up a regular perturbation expansion for $u(\cdot, \cdot, \epsilon)$ and find the first correction to the leading order solution found above.

- (8) (a) Explain the difference between pointwise convergence and asymptotic convergence. Illustrate with the particular example of power series.
 (b) Consider the map that associates to a function $f(z)$ its asymptotic expansion as $z \rightarrow z_0$, where z_0 is a point of the complex plane, including infinity. Thus $f(z) \sim g_N(z)$ where

$$g_N(z) \equiv \sum_{n=0}^N a_n \phi_n(z), \quad \text{with} \quad \lim_{z \rightarrow z_0} \left| \frac{f(z) - g_N(z)}{\phi_N(z)} \right| = 0,$$

for some sequence of order functions $\phi_n(z)$, $n = 0, \dots, N$. Is this mapping invertible? Discuss and illustrate with examples.

- (c) Is the mapping associative? Is it distributive? Discuss.

Problem 1

Aug 2015



$$r_1(t) \quad \left\{ \begin{aligned} m_1 \ddot{r}_1 &= - \frac{GMm_1}{|r_1 - r_2|^2} - k(r_1 - r_2 - d) \end{aligned} \right. \quad (1)$$

$$m_2 \ddot{r}_2 = - \frac{GMm_2}{|r_1 - r_2|^2} + k(r_1 - r_2 - d) \quad (2)$$

where $d =$ length of spring at rest

a) Let $L = d$ and $T = \sqrt{\frac{m_2}{k}}$ and define

$$r = zL \quad \text{and} \quad t = \tau T.$$

\swarrow non-dim \searrow

$$\Rightarrow \frac{dr}{dt} = \frac{d(zL)}{dt} = \frac{L}{T} \frac{dz}{d\tau} = \frac{L}{T} \dot{z}$$

Let's non-dim eqn (1):

$$m_1 \frac{L}{T^2} \ddot{z}_1 = - \frac{GMm_1}{L^2(z_1 - z_2)^2} - kL(z_1 - z_2 - 1)$$

$$\ddot{z}_1 = - \frac{GMT^2}{L^3(z_1 - z_2)^2} - \frac{kT^2}{m_1} (z_1 - z_2 - 1) \quad \text{Let } \epsilon = \frac{m_2}{m_1} \ll 1$$

$$\left\{ \begin{aligned} \ddot{z}_1 &= - \frac{GMT^2}{L^3(z_1 - z_2)^2} - K \epsilon (z_1 - z_2 - 1) \end{aligned} \right. \quad (3)$$

$$\left\{ \begin{aligned} \ddot{z}_2 &= - \frac{GMT^2}{L^3(z_1 - z_2)^2} + K (z_1 - z_2 - 1) \end{aligned} \right. \quad (4)$$

b) Neglecting gravity:

$$\begin{cases} \ddot{z}_1 = -k\varepsilon(z_1 - z_2 - 1) & (5) \\ \ddot{z}_2 = k(z_1 - z_2 - 1) & (6) \\ \dot{z}_i(0) = 0 \end{cases} \Rightarrow z_1 = \frac{\dot{z}_2}{k} + z_2 + 1 \quad (7)$$

$$\Rightarrow \frac{\ddot{z}_2}{k} + \ddot{z}_2 = -k\varepsilon \left(\frac{\dot{z}_2}{k} + z_2 + 1 - z_2 - 1 \right)$$

Ansatz: $z_2 = \bar{z} + \varepsilon \bar{z}_1 + \varepsilon^2 \bar{z}_2 + \dots$

$$\mathcal{O}(1): \ddot{\bar{z}} + k\bar{z} = 0 \quad \text{let } u = \bar{z}$$

$$\ddot{u} = -ku$$

$$u = k(\sin \tau + \cos \tau)$$

$$\ddot{\bar{z}} = k(\sin \tau + \cos \tau)$$

$$\dot{\bar{z}} = k(\cos \tau - \sin \tau) + a \quad \dot{\bar{z}}(0) = -k + a = 0 \\ a = k$$

$$\bar{z} = k(-\sin \tau - \cos \tau) + kt + \bar{z}(0)$$

$$z_2 \sim k(-\sin \tau - \cos \tau) + kt + z_2(0) \quad \text{as } \varepsilon \rightarrow 0$$

z_1 can be found using eqn (7)

c) This can be done through a process similar to the one above but including the gravity term. By shrinking the Earth to a point, we can use $z_0 \sim 0$ and it would be convenient to use $\frac{1}{z^2} = \sum_{n=0}^{\infty} (z+1)^n$.

Problem 2

Aug 2015

$$f(z) = \frac{1}{\sqrt{z^2-1}} \operatorname{atan}\left(\frac{1}{\sqrt{z^2-1}}\right)$$

a) Branch points:

$$\begin{aligned} \Gamma: z^2-1 &= 0 \\ z &= \pm 1 \end{aligned}$$

Note: $z = \pm 1$ are also essential singularities

$$\operatorname{atan}(x) = \frac{1}{2i} \log\left(\frac{1-xi}{1+xi}\right)$$

BP's for log at 0 and ∞

$$\infty: 1+xi = 0$$

$$x = i$$

$$z^2-1 = -1$$

$$z = 0$$

$$0: 1-xi = 0$$

$$x = -i$$

$$z^2-1 = 1$$

$$z = 0$$

Check if $z=0$ is a bp

$$\log\left(\underbrace{1-\sqrt{p_1 p_2}}_1 e^{i \frac{\theta_1 - \theta_2}{2}}\right) - \log\left(\underbrace{1+\sqrt{p_1 p_2}}_2 e^{i \frac{\theta_1 + \theta_2}{2}}\right) \stackrel{?}{=} \log\left(\underbrace{1-\sqrt{p_1 p_2}}_3 e^{\frac{\theta_1 - \theta_2}{2} + 2\pi i}\right) - \log\left(\underbrace{1+\sqrt{p_1 p_2}}_4 e^{\frac{\theta_1 - \theta_2}{2} + 2\pi i}\right)$$

$$\ln(\text{stuff}) + \arg(1) - \arg(2) = \ln(\text{stuff}) + \arg(3) - \arg(4)$$

$$\phi_1 - \phi_2 = \phi_1 + 2\pi - \phi_2 - 2\pi$$

So $z=0$ is not a bp.

Let's also check if ∞ is a bp

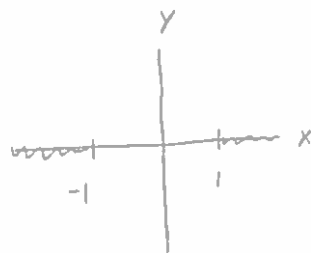
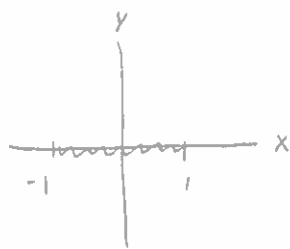
$$z = \frac{1}{s}$$

$$\Rightarrow \frac{s}{\sqrt{1-s^2}} \operatorname{atan} \left(\frac{s}{\sqrt{1-s^2}} \right) \xrightarrow{\text{as } s \rightarrow 0} \operatorname{atan}(0) = 0$$

So ∞ is not a bp either.

Thus our only branch points are $z = \pm 1$

Proposed branch cuts:



$$K(x, y, z) = A + F\left(\frac{x}{z^2}\right) + G\left(\frac{y}{z}\right)$$

$$u_t = \partial_x (K \partial_x u) + \partial_y (K \partial_y u) + v\left(\frac{x}{z^2}\right) u$$

$$\text{Let } w = \frac{x}{z^2} \text{ and } z = \frac{y}{z} \Rightarrow \partial_x \mapsto \partial_x + \frac{1}{z^2} \partial_w \quad \& \quad \partial_y \mapsto \partial_y + \frac{1}{z} \partial_z$$

$$\Rightarrow u_t = (\partial_x + \frac{1}{z^2} \partial_w) [K (\partial_x + \frac{1}{z^2} \partial_w) u] + (\partial_y + \frac{1}{z} \partial_z) [K (\partial_y + \frac{1}{z} \partial_z)] + v(w) \cdot u$$

$$\text{Ansatz: } u = \bar{u} + \varepsilon u_1 + \varepsilon^2 u_2 + \dots$$

$$\mathcal{O}\left(\frac{1}{z^4}\right): \partial_w (K \partial_w \bar{u}) = 0 \Rightarrow u(x, y, z, t)$$

$$\mathcal{O}\left(\frac{1}{z^3}\right): \partial_w (K \partial_w u_1) = 0 \Rightarrow u_1(x, y, z, t)$$

$$\mathcal{O}\left(\frac{1}{z^2}\right): \partial_w (K \partial_w u_2) + \cancel{\partial_w (K \partial_w \bar{u})} + \partial_w (K \partial_x \bar{u}) + \partial_z (K \partial_z \bar{u}) = 0$$

$$\langle \partial_w (K \partial_w u_2 + K \partial_x \bar{u}) \rangle_w + \langle \partial_z (K \partial_z \bar{u}) \rangle_w = 0$$

\uparrow periodic \uparrow indep w

$$K (\partial_w u_2 + \partial_x \bar{u}) = A$$

$$\langle \partial_w u_2 + \partial_x \bar{u} \rangle_w = \left\langle \frac{A}{K} \right\rangle_w$$

$$\partial_x \bar{u} = A (\langle K \rangle_w^h)^{-1}$$

$$K (\partial_w u_2 + \partial_x \bar{u}) = \langle K \rangle_w^h \partial_x \bar{u} \Rightarrow \bar{u}(x, y, t)$$

$$\mathcal{O}\left(\frac{1}{z}\right): \partial_w (K \partial_w u_3) + \cancel{\partial_w (K \partial_w u_1)} + \partial_w (K \partial_x u_1) + \partial_z (K \partial_z u_1) + \cancel{\partial_y (K \partial_z \bar{u})} + \partial_z (K \partial_y \bar{u}) = 0$$

$$\langle \partial_w (K \partial_w u_3 + K \partial_x u_1) \rangle_w + \langle \partial_z (K \partial_z u_1 + K \partial_y \bar{u}) \rangle_w = 0$$

$$\langle K \rangle_w (\partial_z u_1 + \partial_y \bar{u}) = B$$

$$\partial_y \bar{u} = B (\langle K \rangle_w^h)^{-1}$$

$$\langle K \rangle_w (\partial_z u_1 + \partial_y \bar{u}) = \langle K \rangle_w^h \partial_y \bar{u}$$

$$\begin{aligned} \theta(1): \partial_w (K \partial_w u_4) + \partial_x (K \partial_w u_2) + \partial_w (K \partial_x u_2) + \partial_z (K \partial_y u_1) + \partial_y (K \partial_z u_1) \\ + v(z) \bar{u} + \partial_x (K \partial_x \bar{u}) + \partial_y (K \partial_y \bar{u}) = u_t \end{aligned}$$

$$\begin{aligned} \langle \underbrace{\partial_w (K \partial_w u_4 + K \partial_x u_2)}_{FA} \rangle_w + \langle \partial_z (K \partial_z u_2 + K \partial_y u_1) \rangle_w + \langle \partial_x (K \partial_w u_2 + K \partial_x \bar{u}) \rangle_w \\ + \langle \partial_y (K \partial_z u_1 + K \partial_y \bar{u}) \rangle_w + \langle v(z) \bar{u} \rangle_w = \langle \bar{u}_t \rangle_w \end{aligned}$$

$$\begin{aligned} \langle \underbrace{v(z) \bar{u}}_{\substack{\text{periodic} \\ \downarrow \\ \text{indep of } z}} \rangle_z + \langle \partial_z (K \partial_z u_2 + K \partial_y u_1) \rangle_z + \langle \langle K \rangle_w^n \bar{u}_{xx} \rangle_z + \langle \partial_y (\langle K \rangle_w (\partial_z u_1 + \partial_y \bar{u})) \rangle_z = \langle \bar{u}_t \rangle_z \\ \langle \langle K \rangle_w^n \bar{u}_y \rangle_z \end{aligned}$$

$$\bar{u}_t = \underbrace{\langle \langle K \rangle_w \rangle_z}_\alpha \bar{u}_{xx} + \underbrace{\langle \langle K \rangle_w \rangle_z^n}_\beta \bar{u}_{yy}$$

$$\therefore \boxed{\bar{u} = \mathcal{F} \left\{ e^{(\alpha x^2 + \beta \eta^2) t} \right\}}$$

$$\text{where } \mathcal{F}(\bar{u}_{xx}) = x^2$$

$$\mathcal{F}(\bar{u}_{yy}) = \eta^2$$

$$y^{(4)} = xy \tag{1}$$

a) For some path C :

$$y = \int_C \hat{y} e^{sx} ds \tag{2}$$

$$\Rightarrow y^{(4)} = \int_C \hat{y} s^4 e^{sx} ds$$

$$\dagger xy = \int_C \hat{y} e^{sx} x ds = \left. \frac{e^{sx} y}{s} \right|_C - \int_C e^{sx} \hat{y}_s ds = - \int_C e^{sx} \hat{y}_s ds$$

$$u = \hat{y}$$

$$v = e^{sx}$$

$$du = \hat{y}_s ds$$

$$dv = x e^{sx} ds$$

Conditions on C :

i) conv. integrals

ii) $e^{sx} \hat{y} \Big|_C = 0$

Plug into (1):

$$\int_C s^4 e^{sx} \hat{y}_s ds = - \int_C e^{sx} \hat{y} ds$$

$$\int_C e^{sx} (s^4 \hat{y} + \hat{y}_s) ds = 0$$

$$s^4 \hat{y} + \hat{y}_s = 0$$

$$\hat{y}_s + s^4 \hat{y} = 0$$

$$\hat{y} = a e^{-\frac{s^5}{5}}$$

where $s = r e^{i\theta}$

Plug into (2):

$$y = a \int_C e^{sx - \frac{s^5}{5}} dx$$

For this to decay as $x \rightarrow \infty$, we need $y \rightarrow 0$.

This will occur when $\text{Re}(s^5) > 0 \because s^5$ will dominate

s ,

$$b) \quad s^5 = r^5 e^{i5\theta}$$

$$\operatorname{Re}(s^5) > 0 \quad \text{if} \quad \cos 4\theta > 0$$

$$-\frac{\pi}{2} + 2\pi k < 5\theta < \frac{\pi}{2} + 2\pi k \quad k = 0, 1, 2, 3, 4$$

$$-\frac{\pi}{10} + \frac{\pi k}{5} < \theta < \frac{\pi}{10} + \frac{\pi k}{5}$$

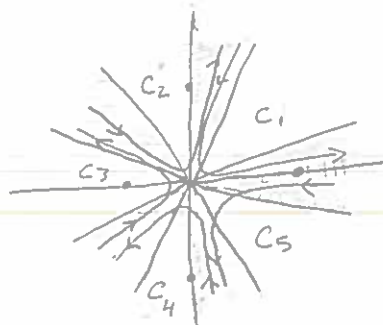
$$k=0: \quad -\frac{\pi}{10} < \theta < \frac{\pi}{10}$$

$$k=1: \quad \frac{3\pi}{10} < \theta < \frac{5\pi}{10} = \frac{\pi}{2}$$

$$k=2: \quad \frac{7\pi}{10} < \theta < \frac{9\pi}{10}$$

$$k=3: \quad \frac{11\pi}{10} < \theta < \frac{13\pi}{10}$$

$$k=4: \quad \frac{3\pi}{2} = \frac{15\pi}{10} < \theta < \frac{17\pi}{10}$$



Choose C to be contour that goes to zero as $x \rightarrow \infty$ and easy to deform thru s.p.

$$\Rightarrow C = C_3$$

$$Y = \int_{C_i} e^{-\frac{s^5}{5} + sx} ds = \int_{C_i} x^\alpha e^{-\frac{s^5}{5} + \xi x^{\alpha+1}} d\xi \quad \begin{array}{l} 5\alpha = \alpha + 1 \\ \alpha = 1/5 \end{array}$$

$$\begin{aligned} s &= x^{1/5} \xi \\ ds &= x^{1/5} d\xi \\ &= \int_{C_i} x^{1/5} e^{-\xi^5/4 + \xi} d\xi \end{aligned}$$

$$h(\xi) = -\frac{\xi^5}{5} + \xi$$

$$h'(\xi) = -\xi^4 + 1 = 0 \quad \xi_k = e^{\frac{k\pi i}{2}} \quad k = 0, 1, 2, 3$$

$$h''(\xi) = -4\xi^3 \neq 0 \quad \forall \xi_k \Rightarrow n=2$$

$$h''(-1) = 4e^{i0} \Rightarrow \alpha = 0$$

We need $\text{Im}(h(z)) = 0$ and $\text{Re}(h(z)) < 0$

$$\text{so } \sin(\alpha + 2\theta_m) = 0 \quad \text{and} \quad \cos(\alpha + 2\theta_m) < 0 \quad m = 0, 1$$

$$\alpha + 2\theta_m = m\pi$$

$$\theta_m = \frac{m\pi}{2}$$

$$\theta_0 = 0 \quad \theta_1 = \frac{\pi}{2}$$

$$\theta_0: \cos(0) = 1 \neq 0$$

$$\theta_1: \cos(\pi) = -1 < 0$$

$$\theta_{\text{SD}} = \frac{\pi}{2}$$

$$y = \int_{C_3} x^{1/4} e^{x^{5/4} h(\xi)} d\xi \sim x^{1/4} e^{x^{5/4} h(-1)} \sqrt{\frac{2\pi}{x^{5/4} |h''(-1)|}} e^{i\pi/2} \quad \text{as } x \rightarrow \infty$$

↑
by Method of SD

$$y(x) \sim x^{1/4} i e^{-4/5 x^{5/4}} \sqrt{\frac{\pi}{2x}} \quad \text{as } x \rightarrow \infty$$

Note: We should deform the C_3 curve
to go through $\xi^* = -1$



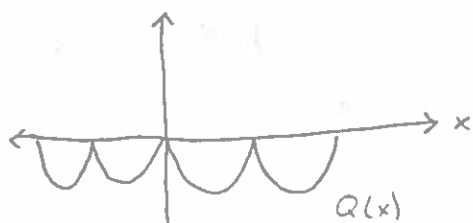
$$\varepsilon y'' + (\cos^2(x) + \lambda) y = 0$$

$$\varepsilon y'' - (-\cos^2(x) - \lambda) y = 0$$

$$Q(x) = -\cos^2(x)$$

$$E = \lambda$$

$$\varepsilon y'' - \underbrace{(Q(x) - E)}_{U(x)} y = 0$$



a) $\min(Q(x)) < E < \max(Q(x))$

$$\boxed{-1 < \lambda < 0}$$

b) We know: $y \sim e^{\frac{s_0}{\varepsilon} + s_1 + \dots}$

$$\text{where } s_0 = w \int^x \sqrt{Q(t) - \lambda} dt$$

$$= w \int^x \sqrt{-\cos^2 t - \lambda} dt$$

$$= ?$$

$$\text{and } s_1 = \frac{1-\lambda}{2(1-\lambda)} \log(-\cos^2 t - \lambda)$$

$$= -\frac{1}{4} \log(-\cos^2(x) - \lambda)$$

$$= ?$$

Given more time, I'd explore various integration techniques for s_1 , and maybe try a Taylor series expansion for s_1 .



Problem 6

Aug 2015

$$\epsilon z^4 + z^2 - 2z + 1 = \epsilon \tag{1}$$

Consider the unperturbed problem:

$$z^2 - 2z + 1 = 0$$

$$(z-1)^2 = 0$$

$$z = 1 \text{ Non-degen} \because \epsilon + 1 - 2 + 1 = \epsilon \checkmark$$

$$\Rightarrow z_2 = 1 + \epsilon^{1/2} a_1 + \dots$$

Plug into (1):

$$\epsilon (1 + \epsilon^{1/2} a_1 + \dots)^4 + (1 + \epsilon^{1/2} a_1 + \dots - 1)^2 = \epsilon$$

$$O(\epsilon): 1 + a_1^2 = 1$$

$$a_1 = 0$$

$$O(\epsilon^2): 4a_2 + a_2^2 = 0$$

$$a_2 = 0 \text{ or } a_2 = -1/4$$

corresponds to $z_1 = 1$ soln

$$\begin{aligned} z_1 &\sim 1 + 0\epsilon \\ z_2 &\sim 1 - 1/4\epsilon \end{aligned}$$

as $\epsilon \rightarrow 0$

Let $x = \epsilon^\alpha z \Rightarrow z = \epsilon^{-\alpha} x$ and plug into (1):

$$\epsilon^{1-4\alpha} x^4 + \epsilon^{-2\alpha} x^2 - 2\epsilon^{-\alpha} x + 1 = \epsilon$$

$$1 - 4\alpha = -2\alpha$$

$$1 = 2\alpha$$

$$\alpha = 1/2$$

$$\epsilon^{-1} x^4 + \epsilon^{-1} x^2 - 2\epsilon^{-1/2} x + 1 = \epsilon$$

$$x^4 + x^2 - 2\epsilon^{1/2} x + \epsilon = \epsilon^2$$

(2)

Consider the unperturbed problem:

$$x^4 + x^2 = 0$$

$$x^2(x^2 + 1) = 0$$

$$x = 0, 0, -i, i$$

↑↑ correspond with z_1 and z_2

$$x_3 = -i + b_1 \varepsilon^{1/2} + \dots$$

$$x_4 = i + c_1 \varepsilon^{1/2} + \dots$$

Plug into (2):

$$(-i + b_1 \varepsilon^{1/2})^4 + (-i + b_1 \varepsilon^{1/2})^2 - 2\varepsilon^{1/2}(-i + b_1 \varepsilon^{1/2}) + \varepsilon = \varepsilon^2$$

$$O(\varepsilon^{1/2}) : -4ib_1 - 2ib_1 + 2i = 0$$

$$b_1 = -1$$

Similarly, $c_1 = -1$

$$\Rightarrow x_3 = -1 - \varepsilon^{1/2}$$

$$x_4 = 1 - \varepsilon^{1/2}$$

Recall $z = \varepsilon^{-1/2} x$

$$\Rightarrow \begin{cases} z_3 \sim -\frac{1}{\sqrt{\varepsilon}} - 1 \\ z_4 \sim \frac{1}{\sqrt{\varepsilon}} - 1 \end{cases}$$

as $\varepsilon \rightarrow 0$

Problem 7

Aug 2015

$$u_t + (\varepsilon + x)u_x = \varepsilon u u_x$$

(1)

a) Let $\varepsilon = 0 \Rightarrow u_t + xu_x = 0$

(2)

Define
$$\begin{cases} z(s) = u(x(s), T(s)) \\ X(0) = x \\ T(0) = t \end{cases}$$

From coeff's of (2) we know:

$$\begin{cases} \frac{dX}{ds} = X(s) \\ \frac{dT}{ds} = 1 \end{cases} \Rightarrow \begin{cases} X(s) = c_1 e^s \\ T(s) = s + c_2 \end{cases} \Rightarrow \begin{cases} X(s) = x e^s \\ T(s) = s + t \end{cases}$$

$$\frac{dz}{ds} = 0 \Rightarrow z(s) = z(0)$$

$$\begin{cases} z(s) = u(x(s), T(s)) \\ z(0) = u(x, t) \end{cases} \quad \text{choose } s = -t$$

$$z(0) = z(-t)$$

$$\therefore \boxed{u(x, t) = u_0(x e^{-t})}$$

b) Ansatz: $u(x, t) = \bar{u}(x, t) + \varepsilon u_1(x, t) + \dots$

where $\bar{u}(x, t) = u_0(x)$

$$u_i(x, 0) = 0 \quad \forall i \geq 1$$

$$\Theta(1): \bar{u}_t + x \bar{u}_x = 0$$

$$\Rightarrow \bar{u}(x, t) = u_0(xe^{-t}) \quad \text{by part (a)}$$

$$\Theta(\varepsilon): u_{1,t} + \bar{u}_x + x u_{1,x} = \bar{u} \bar{u}_x$$

$$\begin{cases} z(s) = u_1(X(s), T(s)) \\ X(s) = x \\ T(s) = 1 \end{cases} \Rightarrow \begin{cases} X(s) = xe^s \\ T(s) = s+t \end{cases}$$

$$\frac{dz}{ds} = \bar{u} \bar{u}_x - \bar{u}_x = g(X(s), T(s))$$

$$\Rightarrow z(s) = z(0) + \int_0^s g(X(v), T(v)) dv = u_1(X(s), T(s))$$

Choose $s = -t$

$$z(-t) = z(0) + \int_0^{-t} g(X(v), T(v)) dv = u_1(xe^{-t}, 0) = 0$$

where $z(0) = u_1(x, t)$. Solve above for u_1 :

$$\therefore u_1(x, t) = - \int_0^{-t} g(xe^v, v+t) dv$$

Problem 8

Aug 2015

a) Let $\Omega \subset \mathbb{C}$, $x_0 \in \Omega$ and f_n be a sequence of fncs.

Ptws: We say $f_n \rightarrow f$ conv ptws if $\forall \varepsilon > 0 \exists N \in \mathbb{N}$ st
 $\forall n > N$ we get $|f_n(x_0) - f(x_0)| < \varepsilon$.

Note: We are only concerned with the fixed pt
 x_0 and N can vary as ε changes.

Asymp: Fix N . We say $f_n \rightarrow f$ conv asymp'ly if
 $\forall \varepsilon > 0 \exists \delta > 0$ st $|x - x_0| < \delta \Rightarrow |f_n(x) - f(x)| < \varepsilon$.

Note: We are only concerned w/ the nbhd of
 x_0 , not x_0 itself and N is fixed.

Ex: In each example, I'll use Ratio test to
show conv.

i) $\sum_{n=0}^{\infty} \frac{x^n}{n!}$

$$\left| \frac{x^{n+1}}{(n+1)!} \cdot \frac{n!}{x^n} \right| = \left| \frac{x}{n+1} \right| \begin{array}{l} \xrightarrow[n \rightarrow \infty]{x \text{ fixed}} 0 \\ \xrightarrow[n \text{ fixed}]{x \rightarrow \infty} \infty \end{array} \begin{array}{l} \therefore \text{ptws conv} \\ \therefore \text{not asymp conv} \end{array}$$

$\sum_{n=0}^{\infty} \frac{n!}{x^n}$

$$\left| \frac{(n+1)!}{x^{n+1}} \cdot \frac{x^n}{n!} \right| = \left| \frac{n+1}{x} \right| \begin{array}{l} \xrightarrow[n \rightarrow \infty]{x \text{ fixed}} \infty \\ \xrightarrow[n \text{ fixed}]{x \rightarrow \infty} 0 \end{array} \begin{array}{l} \therefore \text{not ptw conv} \\ \therefore \text{asymp conv} \end{array}$$

b) ?

c) Distributive

Sps $f \sim \tilde{f}$ and $g \sim \tilde{g}$ as $z \rightarrow z_0$ for both. Then yes,

$$f + g \sim \tilde{f} + \tilde{g}$$

so \sim is distributive.

Now sps we also have $h \sim \tilde{h}$ as $z \rightarrow z_0$.

Making use of distributive...

$$\Rightarrow (f + g) + h \sim \widetilde{(f + g)} + \tilde{h} \sim (\tilde{f} + \tilde{g}) + \tilde{h} = \tilde{f} + \tilde{g} + \tilde{h}$$

$$f + (g + h) \sim \tilde{f} + \widetilde{(g + h)} \sim \tilde{f} + (\tilde{g} + \tilde{h}) = \tilde{f} + \tilde{g} + \tilde{h}$$

Thus \sim is associative,

\uparrow
 $\because +$ is
associative